

Distributed Interference Compensation for Multi-channel Wireless Networks

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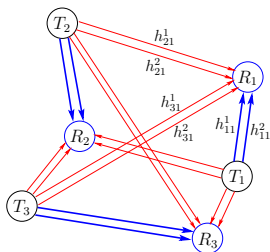
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Motivation



- Communication networks with **multiple interfering channels**:
 - ▶ Wireless ad hoc networks with frequency selective channels.
 - ▶ Multi-cell OFDM networks with inter-cell interference.
 - ▶ DSL with crosstalk.
- How to mitigate interference and improve network performance?

Multi-channel Wireless Network Model



- Several transmitter-receiver pairs (users).
 - ▶ **Single-hop** and **half-duplex** transmissions.
- Channels gains are fixed (slow fading).
- Concurrent transmissions cause mutual interference.
- No centralized controller.
- How can interference mitigation be done **efficiently** in a **distributed** way with limited (**scalable**) information exchange?

Related Work and Our Contributions

- Most previous work has focused on maximization of **achievable rate region**:
 - ▶ Partially characterized capacity regime [Costa'85].
 - ▶ Centralized optimal power allocation for interference channel. [Cendrillon et. al.'05].
 - ▶ Decentralized algorithms: iterative water-filling, [Yu et. al.'02], signal space partitioning [Popescu et. al.'04].

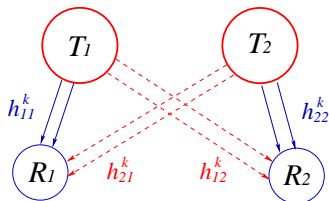
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 - ▶ Decentralized algorithms: iterative water-filling, [Yu et. al.'02], signal space partitioning [Popescu et. al.'04].
- Our contributions:
 - ▶ Maximize **total network utility** (total rate is a special case).
 - ▶ **Distributed** price-based algorithm that achieves **global** optimality in certain cases.
 - ▶ **Fast** and **robust** convergence.

Talk Outline

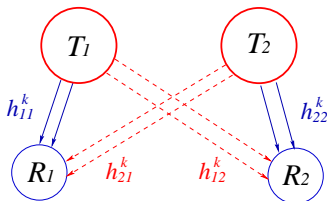
- Network model and performance metric.
- **Asynchronous distributed pricing (ADP)** algorithm for power control.
- Optimality and convergence analysis:
 - ▶ **Primal** ADP algorithm
 - ▶ **Dual** ADP algorithm

Network Model



- I transmitter-receiver pairs (**users**).
- K parallel channels for all users.

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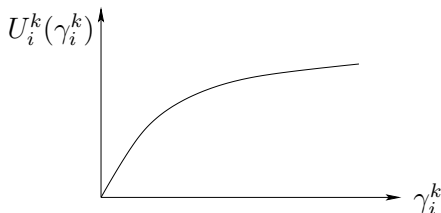
- I transmitter-receiver pairs (**users**).
- K parallel channels for all users.
- User i transmits in channel k with power $p_i^k \geq P_i^{\min}$ such that

$$\sum_{k=1}^K p_i^k \leq P_i^{\max} \quad (\text{individual total power constraint})$$

- Received Signal-to-Interference plus Noise Ratio (SINR) in channel k for user i :

$$\gamma_i^k = \frac{p_i^k h_{ii}^k}{n_0^k + \sum_{j \neq i} p_j^k h_{ji}^k}$$

Utility Functions



- User i 's QoS preference is given by utility

$$U_i = \sum_k U_i^k(\gamma_i^k).$$

- ▶ **Separable** across channels.
 - ▶ $U_i^k(\gamma_i^k)$ is increasing and strictly concave in γ_i^k .
 - ▶ Rate-adaptive applications with **elastic** demands.
 - ▶ **Private** information, only known to the user.
- **Network performance = total network utility**

Total Utility Maximization Problem

- **Goal:** allocate power in a **distributed** way to **maximize total utility**.
- **Challenges:**
 - ▶ Power assignment across channels is coupled due to individual total power constraints.
 - ▶ Power assignment across users is coupled due to mutual interferences.
 - ▶ Objective function may not be concave in power.
- **Our approach:** **distributed** cooperation by exchange of **interference prices**.

Asynchronous Distributed Pricing (ADP) Algorithm

- Repeat two steps asynchronously across users.
 - ▶ **Price announcement:** users announce **prices** in each channel, which reflect sensitivities to interferences.
 - ▶ **Power updates:** users update powers to maximize their **surplus** (**utility - payment**).

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- Prices can be interpreted as a **Pigovian tax** that internalizes the negative externality caused by interference.
- **Primal** and **Dual** ADP differ in how to deal with the coupling across channels due to individual total power constraints.

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- **Power Update**: user i updates the power in all channels to maximize surplus (need **local channel measurements**)

$$\begin{aligned} \max \quad & \sum_{k=1}^K \left(\underbrace{U_i^k(\gamma_i^k(p_i^k))}_{\text{Utility}} - \underbrace{p_i^k \sum_{j \neq i} \pi_j^k h_{ij}^k}_{\text{Payment}} \right) \\ & \underbrace{\hspace{10em}}_{\text{Surplus in channel } k} \\ \text{s.t.} \quad & \sum_{k=1}^K p_i^k \leq P_i^{\max} \end{aligned}$$

Properties of Primal ADP

- **Optimality**: a power and price profile $(\mathbf{p}^*, \boldsymbol{\pi}^*)$ is a fixed point of the Primal ADP algorithm if and only if \mathbf{p}^* satisfies the Kuhn-Tucker condition of the total utility maximization problem.
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 - ▶ A **unique** fixed point corresponds to the **global optimal** power allocation.
- **Convergence**: depends on system parameters
 - ▶ Game theoretic approach: converges with unique or multiple fixed points.
 - ▶ Contraction mapping approach: converges to a unique fixed point.

Fictitious Power-Price Game

- Model each user as two **fictitious players** in a game:
 - ▶ **Price player** chooses prices to maximize payoff

$$S^{price}(\boldsymbol{\pi}_i) = - \sum_{k=1}^K \left(\pi_i^k - \left| \frac{\partial U_i^k(\gamma_i^k)}{\partial (\sum_{j \neq i} p_j^k h_{ji}^k)} \right| \right)^2$$

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- Primal ADP algorithm corresponds to the **best response updates** of the fictitious game.
 - ▶ A fixed point of the algorithm is a Nash Equilibrium (NE) of the game.
- **Convergence of algorithm = convergence of best response updates**
 - ▶ Fast convergence when game is **supermodular**.

Convergence as a Supermodular Game

- **Supermodular game:**

- ▶ A class of games with **strategic complementarities**.
- ▶ Each player's payoff S_i has **increasing differences**:

$$\frac{\partial^2 S_i}{\partial x_i \partial x_j} \geq 0$$

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- ▶ Key properties:
 - (1) An NE exists.
 - (2) The best response updates converge with proper initializations.
 - (3) If the NE is unique, then the asynchronous best response updates globally converge to it.

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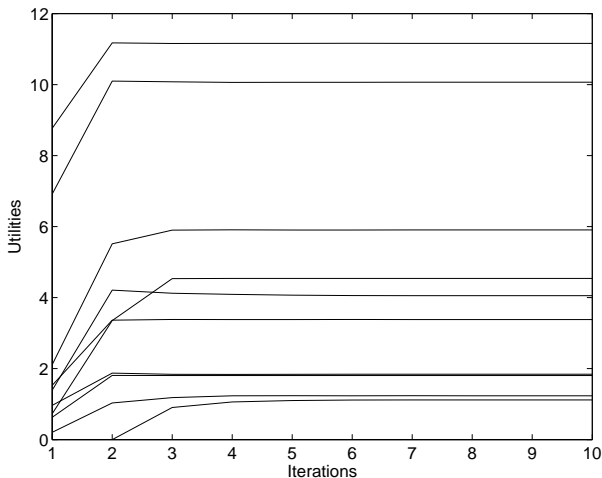
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- **Prop:** when $K = 1, 2$, with suitable restrictions on utilities and users, the fictitious game is supermodular, and

- ▶ The Primal ADP algorithm converges with proper initializations.
- ▶ **If there is a unique fixed point, the algorithm globally converges to it.**

Convergence of Primal ADP



$$U_i = \sum_{k=1}^K \log(1 + \gamma_i^k), \text{ 20 channels, 10 users}$$

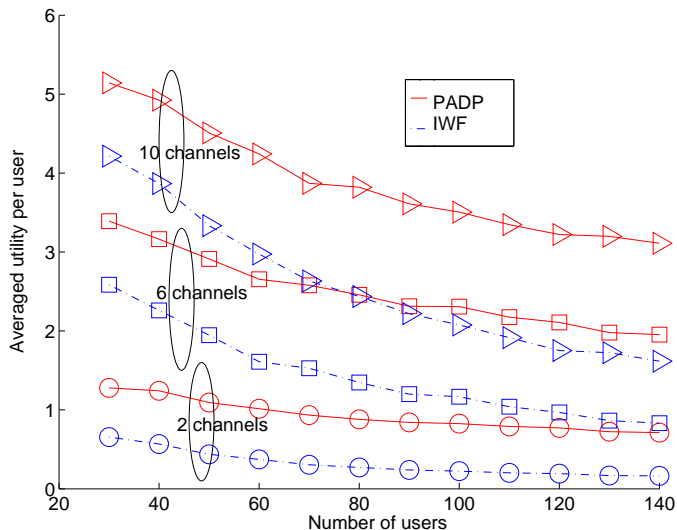
Convergence Analysis: Contraction Mapping

- Primal ADP **converges globally to the unique optimal solution** for:
 - ▶ Two users and multiple channels.
 - ▶ $U_i = \sum_{k=1}^K \log(1 + \gamma_i^k)$.
 - ▶ Small normalized interference: $h_{ji}^k/h_{ii}^k \leq \zeta$ for all users and channels.

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- Compare: **Iterative Water-Filling** (IWF) [Yu et. al.'02]
 - ▶ No exchange of price information.
 - ▶ Each user chooses power to maximize $\sum_{k=1}^K \log(1 + \gamma_i^k)$.
 - ▶ Converges under similar conditions (**not necessarily optimal**).
- Primal ADP achieves better performance than IWF.

Comparison of PADP and IWF



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 - ▶ User announces interference price π_i^k as before.
 - ▶ User chooses power p_i^k to maximize surplus in channel k

$$\max_{p_i^k \in [P_i^{\min}, P_i^{\max}]} U_i^k(\gamma_i^k(p_i^k)) - p_i^k \left(\sum_{j \neq i} h_{ij} \pi_j^k + \mu_i \right).$$

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- **Dual Iterations:** update the dual prices as

$$\mu_i(t) = \left[\mu_i(t^-) + \kappa \left(\sum_{k \in \mathcal{K}} p_i^k(t^-) - P_i^{\max} \right) \right]^+.$$

- Solves the **dual** of the total utility maximization problem.

Convergence of Dual ADP

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- Define the **coefficient of relative risk aversion** of a utility $U_i^k(\gamma_i^k)$ to be

$$Q_i^k(\gamma_i^k) = -\frac{\gamma_i^k U_i^{k''}(\gamma_i^k)}{U_i^{k'}(\gamma_i^k)}.$$

- ▶ larger $Q_i^k(\gamma_i^k) \Rightarrow$ “more concave” U_i^k .

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▶ larger $Q_i^k(\gamma_i^k) \Rightarrow$ “more concave” U_i^k .

- **Prop:** If for each user i :

(1) $P_i^{\min} > 0$, and

(2) $Q_i^k(\gamma_i^k) \in [1, 2]$ for all feasible SINR γ_i^k ;

then there is a unique optimal power allocation, and the Dual ADP algorithm globally and geometrically converges to it with small enough stepsize κ .

Convergence of Dual ADP

- The constraint $Q_i^k(\gamma_i^k) \in [1, 2]$ ensures the problem is **concave** in transformed variables $\log(p_i^k)$ [Chiang'05].

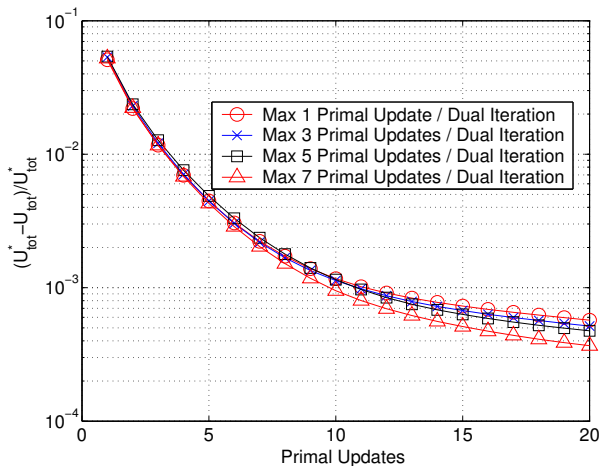
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- Convergence with **constant step-size** κ depends on the **Lipschitz** condition for the gradient of the dual function.
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- Convergence with **constant step-size** κ depends on the **Lipschitz** condition for the gradient of the dual function.
 - ▶ The dual function is not separable across users (different from dual decomposition in wireline networks [Low and Lapsley'99])
- The proof needs “separation of time-scales”:
 - ▶ The Primal Updates need to converge between two successive dual iterations.
 - ▶ Simulations show that the algorithm converges **without** separation of time-scales.

Convergence of Dual ADP



$$U_i = \sum_{k=1}^K \log(\gamma_i^k), \text{ 16 channels, 50 users}$$

Conclusions

- Presented distributed power control algorithm for multi-channel wireless networks.
- Users exchange **price information** to reflect their sensitivities to interference (**Pigovian tax**).
- Proved **optimality** and **convergence** of **Primal** and **Dual** ADP algorithms in various cases.
- Observed convergence in more general settings.
- Currently extending to multi-hop networks with joint scheduling and power control.